An Embedded Iris Image Acquisition Research

Dangui Chen\textsuperscript{1}, Guojun Qin\textsuperscript{2}

\textsuperscript{1}School of Information Science and Engineering, Hunan International Economics University
Changsha, China, postcode: 410205
\textsuperscript{2}School of Mechanical Engineering, Hunan International Economics University
Changsha, China, postcode: 410205

Abstract

In view of the limitation of traditional identification, it is easy to lose and copy keys, cards or ID cards, and it is easy to forget the password. Here, an embedded application system was designed based on the iris identification technology, the functions of gathering, inputting, and registering the iris information and identification can be realized. The system architecture was designed by using the embedded microprocessor of advanced RISC machines (ARM), which is used as the core. The iris sensor was used to gather the iris information, and the development of software was accomplished with the embedded OS Windows CE. The system can be used on the company entrance guard system, customs security of airport and criminal identification.

Keywords: iris recognition, image acquisition, the OS of Windows CE, advanced RISC machines (ARM), embedded visual C++ (EVC)

Copyright © 2017 Institute of Advanced Engineering and Science. All rights reserved.

1. Introduction

Iris recognition is a high-precision biometric identification technology with the advantages of uniqueness, stability, non-invasive. Iris image's quality affects the performance of the recognition algorithms. The ease use and robustness in the recognition system is also affected by the image acquisition method, iris image acquisition plays an important role in the whole system. The iris has distinct textures and details in automated biometric identification systems [1]. Because there were the advantages of non-invasiveness, uniqueness, stability and low false recognition rate in iris recognition, the iris is a highly accurate biometric identifier. The dramatic growth in practical applications for iris biometrics has been accompanied by relevant developments in the underlying algorithms and techniques.

A typical iris recognition system includes image acquisition, image pre-processing, feature extraction and template creation, feature matching and making decision [2, 3]. The diameter of iris is about 11mm. The iris has a very complex composition, a variety of structural texture and a variety of pigment texture are included. The color of iris is different between different races. ISO iris image format standard noted that the accepted iris diameter is 150 pixels or more [4]. With these physiological characteristics and the image acquisition requirement, it is not easy to capture iris images in practice. The iris image's quality will greatly affect the performance of the recognition algorithms, iris image acquisition is a key step and plays an important role in the iris recognition.

In 1991, Johnson first reported to realize an iris recognition system [5]. Subsequently, the prototype iris recognition systems including the basic iris image acquisition part was documented by Daugman and Wildes [6, 7]. Both of the systems require the operator to self-position his eye region in front of the cameras. There are lots of commercial iris image acquisition platforms later. Some of these based on PC and others are based on embedded system. Some of them need the user's fully self-position to help to acquire iris image. Most of these systems have iris positioning technology which can conduct the user's self-position. However, these systems work in a short distance and still need the user's cooperation.

After the basic principles of iris image acquisition is analyzed, the sensor embedded iris information acquisition and application system are presented in this study, it includes the front-end iris sensor acquisition system (lens, image sensor, image processing equipment) and terminal control system (mainly based on the ARM920T core Samsung S3C2410CPU, memory...
modules, LCD touch display module, power section, information acquisition and processing software), two parts are connected by RS232 interface. In iris recognition, the existing back-end information collection management system is generally based on PC platform, it is not easy to move, information collection on-site and data analysis will be difficult. With maturity of hardware and software resources, the development has been rapid in the application of embedded system. Embedded system devices based on Windows CE usually have small size, light weight, low power consumption, network, powerful, user-friendly interface and good stability, the application system of iris sensor embedded information collection is designed in this study, it is able to conduct on-site identity information collection and analysis of data entry.

2. Materials and Methodology
2.1. Composition and Works of Iris Information Acquisition and Application System

Iris information acquisition application system includes three parts with the sensor signal acquisition system, image processing system, and data analysis and transaction management system, as is shown in Figure 1. Sensor signal acquisition system is responsible for locating and collecting of the iris information. The image processing system is that the collected iris image is pre-processed, and feature is extracted by high-performance digital signal processing (digital signal processing, DSP) chips [8, 9]. Data analysis and transaction management system is based on ARM9 embedded terminal, it is responsible for the link between the user iris feature information and its name and identification (identification, ID), and then they are stored in the database, and a user template is created, its information is storaged, it is used for registration and user identification [10, 11].

![System Composition Block Diagram](image)

**Figure 1. System Composition Block Diagram**

a) Iris Information Acquisition System Architecture Design

Left part of the figure are the time domain waveforms, the right part are the spectrogram, and the original voice, white noise (white), noisy speech and enhanced speech is respectively from the top to down. Calculating SNR $\text{SNR}_{\text{in}} = 5\,\text{dB}$ before noisy speech enhancement, the filtered signal to noise ratio $\text{SNR}_{\text{out}} = 8.4\,\text{dB}$. After taking the white noise, the speech enhancement SNR efficiency.

Iris information acquisition system hardware includes iris acquisition module, iris recognition module, embedded core processor, memory unit, the user interface unit and communication interface unit.

b) CMOS Photoelectric Sensor

There are high integration, low power consumption, low cost, good image quality and other characteristics in the CMOS image sensor, OmniVision's OV7110 is chosen as image sensor in the system. OV7110 is a grayscale digital CMOS image sensor, which can achieve the resolution of 640 pixels × 480 pixels. Tests prove that the extent of the resolution can ensure a more complete view of the iris details, it is enough to be used as identification judgment, the iris pattern can be clearly seen in the eye. OV7610 and OV7110 parameter index is consistent with the functions, the only difference is that there is only the Y component in the output of OV7110, i.e., only the gray scale values, while there are the U, V components in the output of OV7610, i.e., a color value. Because the iris information mainly lies in the different of iris texture, so there is the only gray collection.
c) Core Processor Choices

Since the system needs that iris image information is collected with timely response, and it is rapidly processed, and there need be a mass storage and convenient operation, user-friendly interface, the internet information is searched easy and fast, and it has good scalability. Therefore, the core processor requires powerful processing capabilities, rich interface, and it supports direct memory access (DMA) mode, there are better real-time and lower power consumption. Meanwhile, in order to simplify software development, processor be needed to have better support to the embedded operating system. Based on the above considerations, a dual-core processor is selected in the system, ADSP-BF533 type DSP is selected as an image processing module, a Samsung S3C2410 processor is selected in the embedded terminal part.

d) Iris Image Processing Module

Iris image processing section uses a type ADSP-BF533 DSP, the processor is a product of the Blackfin series, it is a new high-performance DSP. Its design needs to meet computing requirements and conditions of low-power design for today's embedded audio, video and communications applications, it is a new 16-bit embedded processor. It is the Micro Signal Architecture (M5A) which is jointly developed by the ADI and Intel, a 32-bit RISC instruction set and dual 16-bit multiply-accumulate (MAC) signal processing functions are combined with the usability of general-purpose microcontroller together.

e) Embedded Core Processors

Embedded core processor is S3C2410. S3C2410 microprocessor is a 16/32 bit RISC processor with low power and highly integrated, it is designed and offered for the Samsung handheld devices, there is a 272-foot field-programmable gate array (FPGA) package, solutions are provided with a low-cost, low-power, high-performance small microcontroller for handheld devices and the general types of applications [9, 12]. The maximum operating frequency is 203 MHz, while threere is the memory management unit (MMU), so that the processor can easily run in Windows CE, Linux and other operating systems, and more complex information is processed. S3C2410A provides the following extensive internal equipment: separate 16 kByte instruction Cache and 16 kByte Data Cache, MMU virtual memory management, LCD (liquid crystal display, LCD) controller (supports STN & TFT), system boot of support NANDFlash, System Manager (chip select logic and SDRAM controller), 3-channel universal asynchronous receiver / transmitter (universal asynchronous receiver / transmitter, UART), 4-channel DMA, 4-channel pulse-width modulation (pulse width modulation, PWM) timer devices, I / O ports, RTC, 8-channel 10-bit analog-to-digital converter (analog to digital converter, ADC) and a touch screen interface, IIC-BUS Interface, IIS-BUS interface, USB host, USB device, SD Master Card & MMC card interface, 2-channel serial peripheral interface (serial peripheral interface, SPI) and internal PLL (phase locked loop, PLL) clock multiplier [13-15].

f) Embedded Peripheral Component

The floor mainly provides power support and interface extensions. Backplane DC is 5 V power supplies, internal conversion 1.8 V is used for processor core, conversion 3.3 V is used for I/O interface circuitry. Communication interface section includes serial port, Ethernet port and USB interfaces, the system is expanded with two serial ports, which are used to communication connection and system debugging for ARM MPU and iris recognition module. In network interface part, because there is no Ethernet S3C2410 internal control module, so a matching control chip is needed, it is Cirrus Logic's CS8900A chip, by using 10BASE-T interface, Ethernet sends and receives data. System expansion USB port is used for an external mouse, and it supports USB synchronization on WinCE. FLASH memory cell is K9F1208 type NandFlash, its capacity is 64 MByte, SDRAM is two HY57V561620, its capacity is 64 MByte. The user interface part is 3.5 inch thin film transistor type (thin film transistor, TFT) color LCD touch screen, 320 pixels x 240 pixels; it is directly conneced to S3C2410 LCD controller. System hardware block diagram is shown in Figure 2.
2.2. Iris Information Acquisition System Software Design

Software design work includes four parts, which are the choice of operating system and kernel customization and transplantation, Bootloader transplant, SPI driver design, application development.

a) Windows CE operating system

Windows CE system is chosen as the underlying operating system. Windows CE is Microsoft’s embedded and mobile computing platforms, it is an open, cutting 32 real-time embedded operating system, the operating system is used to electronic devices which like handheld computers, and compared with other desktop version of the Windows operating system, it has a good reliability, real-time high, the core characteristics of small size, there is only 8-32 MByte of ROM in a typical Windows CE devices, while the smallest Windows CE kernel is only 500 kByte. Windows CE is designed to be a highly modular operating system, it accommodates different types of smart devices, and it meets image size requirements for different operating system, Windows CE graphical user interface is very well.

b) Bootloader transplant

Bootloader is the operating system kernel or a short running program before user application program runs. Through this program, you can initialize the hardware equipment, the memory space map is established, and right environment is ready for the final call operating system kernel or user application program.

On S3C2410, Windows CE Bootloader is implementing into two, which are followed Nboot (nandflash bootloader) and Eboot (ethernet bootloader), they were used to boot loader mode and download the operating system. Execution order of Boot Loader is showed in Figure 3 [8].
c) Windows CE kernel customization and system migration

In Windows CE kernel customization and operating system migration, Platform Builder development tool is used, the appropriate hardware platform BSP (board support package, BSP) and hardware support are added, such as a USB mouse function, network drives, MFC controls, Chinese support. To modify the registry information platform.reg, the appropriate network environment is changed, the same network segment is set with the PC, loading serial peripheral interface (serial peripheral interface, SPI) driver. After configuration, to export the software development kit (software development kit, SDK), the custom operating system is compiled. The resulting image file is downloaded to the target board via Ethernet.

d) SPI-driven design

A driver is a abstraction physical device or virtual device function software, drivers manage the operations of these devices, and equipment function is export to the operating system and applications. According to different of export interface drivers, windows CE driving can be divided into the native device driver (native device driver) and streaming driver (streams device driver). The machine device driver is integrated into the Windows CE platform device. Streaming driver is also known the install driver; the user-mode dynamic link library (dynamic link library, DLL) is dynamically loaded by the Device Manager (device.exe).

In Windows CE, the streaming device driver is responsible for the abstract file, the application will be able to provide application programming interfaces (application programming interface, API) (including readfile, writefile, IControl, etc.) and to read and write for the system. When application program accesses the device by using API File, the request (Filesys.exe) filter through the file system is sent to the device.exe, device.exe calls streaming driver interface on request, to complete the interaction with the hardware.

2.3. Application development

The software part of the system mainly completes the initia, data analysis and processing, PC display and operating functions. In development of master control program, eVC++ 4.0 development tools are used, the C++ code is directly compiled to CPU instructions by eVC++ 4.0, it uses win32 application programming interface (win32API) to access the Windows CE functionality, while it is to help development of graphical user interfaces (graphical user interface, GUI) and COM applications by using MFC (microsoft foundation classes) or Active Template Library (active template library, ATL).

The serial port and baud rate is opened by CreateFile function. Baud rate, stop bits, parity bit is set, the received data is tested, and database information is compared, which is sent to the host computer through UART port, to read and writeserial port via ReadFile and WriteFile, and sound and light alarm is set on the input identification information, iris information is accessed, the user name and ID information registration, delete, and save function are achieved, the user identify is identified, finally, the serial port is closed through the CloseHandle function. System software flow is shown in Figure 4.

3. Experiment Analysis

A set of colored iris diagnostic images are collected by this study in Figure 5, they is with clear screen, and the texture characteristics is highlight [16].

In Figure 5, the upper part is a healthy normal iris, and the lower part is a patient's iris. Medical iris is based on the morphology; morphological changes are observated in the human iris, and by inference and analysis to predict the health of the human body, the occurrence of the disease and physical rehabilitation [17, 18].

To improve the image acquisition system's performance, major research focuses on increasing the working distance, reducing the user’s cooperation, changing the illumination mode, extending the depth of field and etc.
3.1. “Stand off” Iris Imaging

Extending the working distance can improve the convenience of the iris recognition system. A typical “stand off” iris recognition system such as Eagle-Eyes is illustrated [19]. Table 1 gives the comparison of different “stand off” iris recognition systems. Although these works successfully suggested that iris recognition at larger distances was feasible, but still there
is no product for iris acquisition working beyond 3 meters. The IAAD system has a long working distance, but it has a lower speed compared to other systems. Venugopalan’s system has a number of ‘burst’ images [20]. Till now, these systems cannot be applied in practice.

### Table 1. Comparison of stand off iris imaging systems

<table>
<thead>
<tr>
<th>Author</th>
<th>Operating distance(m)</th>
<th>Iris sensor’s resolution</th>
<th>Number of camera</th>
<th>Illumination</th>
<th>Focal length(mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Our system</td>
<td>1.5</td>
<td>1394×1024</td>
<td>2</td>
<td>LED(810nm)</td>
<td>160</td>
</tr>
<tr>
<td>Dong et al. [2009] [22]</td>
<td>3</td>
<td>4-mega pixels</td>
<td>2</td>
<td>\</td>
<td>300</td>
</tr>
<tr>
<td>Bashir et al., [2008] [19]</td>
<td>6</td>
<td>640×480</td>
<td>3</td>
<td>NIR laser</td>
<td>\</td>
</tr>
<tr>
<td>Venugopalan et al. [2011] [20]</td>
<td>12</td>
<td>21.1megapixel</td>
<td>1</td>
<td>LED(850nm)</td>
<td>800</td>
</tr>
<tr>
<td>De Villar et al. [2010] [21]</td>
<td>30</td>
<td>2592×1944</td>
<td>2</td>
<td>\</td>
<td>\</td>
</tr>
</tbody>
</table>

### Table 2. Comparison of variety of illumination for iris acquisition

<table>
<thead>
<tr>
<th>Author</th>
<th>Method of illumination</th>
<th>Wavelengths(nm)</th>
<th>Image Sensor</th>
</tr>
</thead>
<tbody>
<tr>
<td>Our system</td>
<td>NIR and Visible light</td>
<td>R,G,B,NIR</td>
<td>Dual-CCD camera</td>
</tr>
<tr>
<td>Gong et al. [2012] [23]</td>
<td>NIR and Visible light</td>
<td>700-800</td>
<td>CCD sensor 640×480</td>
</tr>
<tr>
<td>Ngo et al. [2009] [24]</td>
<td>NIR and Visible light</td>
<td>400-1550</td>
<td>Si camera 640×480</td>
</tr>
<tr>
<td>Ross et al. [2009] [25]</td>
<td>NIR</td>
<td>950-1700</td>
<td>InGaAs 320×256</td>
</tr>
<tr>
<td>Grabowski et al. [2009] [26]</td>
<td>Visible light, side-</td>
<td>2268×1512</td>
<td>/</td>
</tr>
<tr>
<td></td>
<td>illumination</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### 3.2. Variety of Illumination Imaging
The typical commercial iris recognition system uses 850nm NIR illumination. Long distance image acquisition needs higher intensity light sources and this may be harm to people’s health. Differences in iris texture across spectral bands are considerable, this can be exploited to enhance iris recognition performance. Nowadays, there emerges different iris illumination mode to improve the iris image’s textures.

We compare the different illumination mode above as shown in Table 2. Visible light was used to improve the recognition accuracy and working distance. Most of these systems illuminated both with visible light and NIR. Different with the CCD or CMOS, short infrared cameras are used. a Si camera is used, or a camera is used based on InGaAs. The aim of these systems is to increase the iris image’s quality and extend the working distance. Experiments show that the performance of these systems is good.

### 3.3. Wavefront-Coded Iris Imaging
Typical commercial systems have a small depth of field about tens of centimeters and require user cooperation. The traditional solution to increased depth of field is to increase the f number of the lens, this hurting the signal-to-noise ratio (SNR). Our designed system is show that wavefront coded system can greatly extend the depth of field of iris imaging without significantly decreasing the SNR.

### 4. Conclusions and Outlook
With the development of society, the importance of identity is increasingly apparent, and because the traditional identification method has its inherent limitations, it can not meet the demands, and challenges are faced in safety performance [14, 27]. In the use of keys, cards, ID cards and other token way, there are easy to lose, theft and counterfeiting and other safety hazards. In the use of password mode, there is the problem which is easy to forget and attack, the more serious is that the identification of these traditional methods can not distinguish
between the true owner and the impostors with object identity, while the body is used with itself physical characteristics, such as biometric identification technology, these problems can be avoided, these features have unique advantages in stability, permanence, uniqueness and security. Compared with other biological characteristics, the iris is a more stable, more reliable physiological characteristics. Further, the iris is the external part of the eye, the iris-based identity authentication system may be non-contact for users. According to statistics, so far, iris recognition error rate is the lowest among all kinds of biometrics. Iris recognition has been widely applied in many fields, such as the company’s daily attendance, criminal identity authentication, airport customs security, information security and other key areas.

In this study, the iris information acquisition system has been researched, high-performance embedded microprocessor S3C2410 is used in the process, and ADSP-BF533-based DSP is applied in iris image processing applications, stable and powerful Windows CE operating system is used as the software platform. And we studied in the iris biometric identification technology and image sensor technology, the human iris information acquisition and identification process has been given, the various functions have been tested in the system, there are characteristics with simple, non-invasive to the body, portable, it can meet the needs of the company access control system, the airport customs security, criminal investigation, and information security and other fields.

Simultaneously, the system also has good scalability, and it can be connected to the national iris repository by extending the Ethernet interface, iris information is inquired, and the iris image information is acquired and timely is uploaded.

Acknowledgements
This study is sponsored by the Scientific Research Project (NO. 14C0653) of Hunan Provincial Education Department, China. This study is sponsored by the National Natural Science Foundation project (51375484) of China.

References